



# TECHNICAL MANUAL COMPUTATION MODULE TYPE 626

**Doc. Ref CD2003L**

This manual applies to units of mod status 11D ONWARDS



BS EN ISO 9001  
Certificate No. FM13141



Affirmed by Declaration  
of Conformity

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## 1. INTRODUCTION

The 626 is a 2-channel LVDT oscillator/demodulator which may also be used with half-bridge and similar inductive-type transducers. There is a common excitation supply, but each channel has separate gain and zero controls. Channel A output is voltage, channel B output may be selected for voltage or current.

A rotary switch provides selection of analogue output modes A, B, Average, Difference and Sum with 5 LEDs to indicate which mode is selected.

When not fitted into a Modular 600 housing, connections are made via a rear-mounted 32-way DIN 41612 edge connector. Output signals are also provided on a front-mounted jack which, together with fine gain and zero controls, are accessible via holes in the panel.

Push-button zero-input switches allow easy checking of amplifier zero adjustments and a master/slave facility removes beating effects in multi-channel systems. An optional sample/hold circuit may be fitted, which allows rapid capture of analogue output signals.

Various excitation voltages and frequencies are easily obtained via link/resistor changes. This, together with the gain range switches and zero range switches, allows use with the complete range of RDP LVDTs and half-bridge transducers.

A bi-colour LED gives an approximate indication of armature position.

When used with the RDP type 600 Backplane and 635/6 Monitor units, separate multiplexed output and excitation signals are automatically selected via an on-board decoding circuit for connection to the monitor signal bus.

### **SPECIAL NOTE          Master/Slave**

1. If this module has been supplied in an RDP housing then it will have been configured as a master or slave as required. To avoid beat-frequency effects only one module per system is configured as a master to control excitation frequency of all other modules. In a system the master is generally the first module (channel 1), top rack of 605/6/7 systems.
2. If this module has been purchased on its own, it will be supplied as a stand-alone unit and can be added to an existing system as it is.
3. If the module needs to be made a slave before adding to an existing system (to eliminate any possible beating effects) then see section 3.11.

NOTE: 626 modules of Mod 11 onwards cannot be made slaves to older pre-Mod 11 modules. If in doubt, contact RDP.

## 1.1 BEFORE POWERING-UP CHECK...

1	The supply voltage is correct to suit the 631/632 unit fitted and input range selected
2	The various plug-in modules are in the correct positions in the housing.
3	The input and output plugs are in the correct sockets. Note that on the housing back-plane all input sockets and all output sockets are of the same type.
4	That each module has a unique address. (see section 3.7)
5	The master/slave link is correctly set (see section 3.11)

NOTE: ensure system is switched OFF when removing or replacing modules in rack. Failure to do so may cause damage to modules.

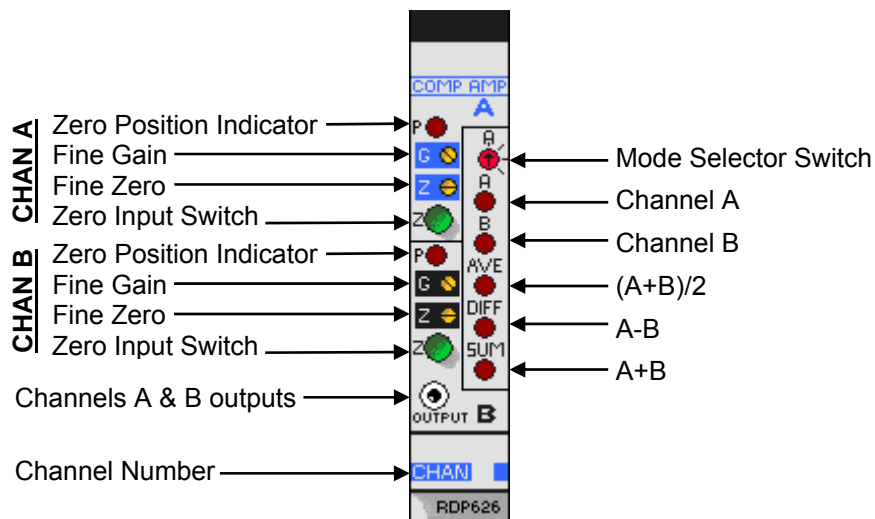
## 1.2 Information on Conformity to EC Directives.

This module is not CE marked because it is intended for use as a component of a larger system. RDP CE mark full modular 600 systems that includes a 60X housing and a 63X power supply where the system is fully populated with either 600 series amplifier/display modules or blank panels.

If the module is part of a full 600 system, refer to the system manual (CD2010) for CE certification.

If the module is not part of the full 600 system, it is the responsibility of the organization/individual producing the system to assess and/or test EMC compatibility.

Fig. 1 Front Panel

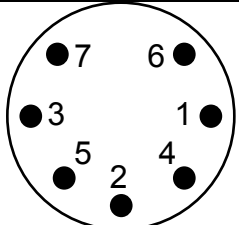


## 2. TRANSDUCER AND OUTPUT CONNECTIONS

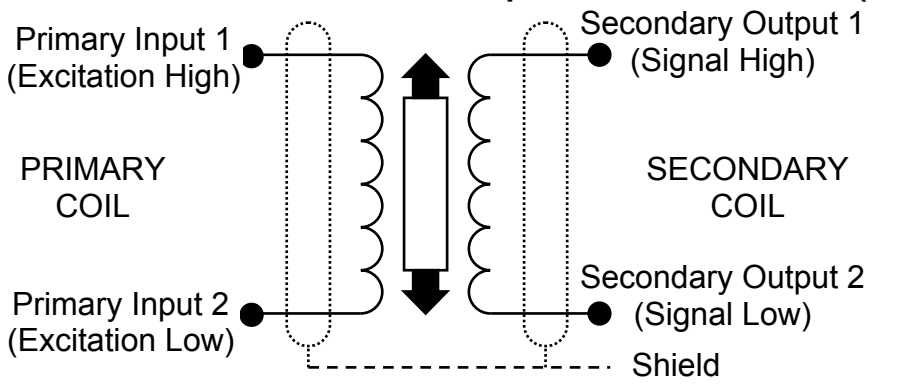
### 2.1 Transducer connections with 600 Backplane.

(Refer also to System Manual CD2010)

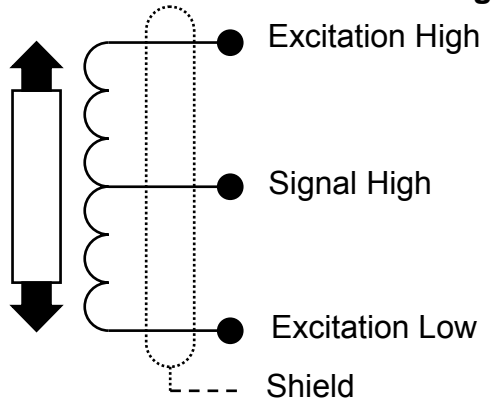
The backplane (rear panel) connectors are arranged in columns of three. Each channel is identified with its number and each connector with a letter - A & B are for the two transducer inputs, where the module is a dual input amplifier, and C identifies the output connector.

<p>When the 626 is used with the RDP Backplane, transducer connections are made via circular DIN connectors as follows:</p> <p>7-pin Channel A connectors 1A to nnA, and 7-pin Channel B connectors 1B to nnB</p>		<p>Input connector (viewed from rear.)</p>
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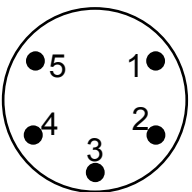
### 2.2 Connections for LVDT displacement Transducer (with backplane)

	<table border="1"> <thead> <tr> <th>Pin</th> <th>Function</th> </tr> </thead> <tbody> <tr> <td>1</td> <td>Excitation High</td> </tr> <tr> <td>2</td> <td>Excitation Low (0V)</td> </tr> <tr> <td>3</td> <td>No connection</td> </tr> <tr> <td>4</td> <td>Sig LO</td> <td rowspan="2">Differential Input</td> </tr> <tr> <td>5</td> <td>Sig HI</td> </tr> <tr> <td>6, 7</td> <td>No connection</td> </tr> <tr> <td>Shell</td> <td>Connect shield to shell of connector</td> </tr> </tbody> </table>	Pin	Function	1	Excitation High	2	Excitation Low (0V)	3	No connection	4	Sig LO	Differential Input	5	Sig HI	6, 7	No connection	Shell	Connect shield to shell of connector
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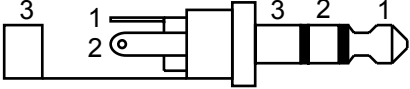
### 2.3 Connections for Half Bridge displacement Transducer (with backplane)

	<table border="1"> <tbody> <tr> <td>Pin 1</td> <td>Excitation High</td> </tr> <tr> <td>Pin 2</td> <td>Excitation Low (0V)</td> </tr> <tr> <td>Pin 3</td> <td>No connection</td> </tr> <tr> <td>Pin 4</td> <td>See below</td> <td rowspan="2">Differential Input</td> </tr> <tr> <td>Pin 5</td> <td>Signal High</td> </tr> <tr> <td>Pin 6, 7</td> <td>No connection</td> </tr> <tr> <td>Shell</td> <td>Connect shield to shell of connector</td> </tr> <tr> <td colspan="2"> <p>Additionally, 1kΩ high stability resistors must be fitted between pins 1&amp;4 and 2&amp;4. Alternatively, they may be fitted to the 626 PCB as detailed in section 3.10</p> </td> </tr> </tbody> </table>	Pin 1	Excitation High	Pin 2	Excitation Low (0V)	Pin 3	No connection	Pin 4	See below	Differential Input	Pin 5	Signal High	Pin 6, 7	No connection	Shell	Connect shield to shell of connector	<p>Additionally, 1kΩ high stability resistors must be fitted between pins 1&amp;4 and 2&amp;4. Alternatively, they may be fitted to the 626 PCB as detailed in section 3.10</p>	
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### 2.4 Connections for Analogue Outputs (with backplane)

<p>Output connector (viewed from rear.)</p>		<p>Outputs: 5-pin Connectors (labelled 1C to nnC)</p> <table border="1"> <tbody> <tr> <td>Pin 1</td> <td>O/P of mode selected on front panel</td> </tr> <tr> <td>Pin 2</td> <td>Output Common (0V)</td> </tr> <tr> <td>Pin 3</td> <td>Channel B Output</td> </tr> <tr> <td>Pin 4</td> <td>No connection</td> </tr> <tr> <td>Pin 5</td> <td>No connection</td> </tr> </tbody> </table>	Pin 1	O/P of mode selected on front panel	Pin 2	Output Common (0V)	Pin 3	Channel B Output	Pin 4	No connection	Pin 5	No connection
Pin 1	O/P of mode selected on front panel											
Pin 2	Output Common (0V)											
Pin 3	Channel B Output											
Pin 4	No connection											
Pin 5	No connection											

## 2.5 Output connections via front panel jack plug.

	PIN	FUNCTION
		1
	2	Channel A output
	3	Output Common (0V)

## 2.6 Input and Output Connections (Without M600 Backplane)

The **DIN 41612** 32-way connector details are:

### **DIN 41612 Connector**

1	Excitation High	Channel A Transducer	
2	Excitation Low (0V)		
3	Screen (0V)		
4	Signal Low		Differential
5	Signal High		
6, 7	No connection		
8	Selected Output (A, B, Sum etc.)		
9	Output common (0V)		
10	Channel B Output only		
11	Excitation High	Channel B Transducer	
12	Excitation Low (0V)		
13	0V		
14	Signal Low		Differential
15	Signal High		
16, 17	No connection		
18	Selected Output	Multiplexed for use with 635/6 only	
19	Channel B Output		
20	Excitation Output		
21	Master/Slave		
22	Output Hold		
23	Limits Reset/Isolated Output 0V		
24-27	Channel Address	Used with 635/6 only	
28	+5VD		
29	0VD		
30	+15V		
31	-15V		
32	0VA		

### 3. CONTROLS

(Refer also to Fig.3 for locations)

#### 3.1 Mode Selector Switch and LEDs

The front panel rotary switch determines the computation mode of the analogue signal appearing at the backplane connector C, pin 1, as detailed below: One of 5 LED indicates which mode is selected.	MODE	OUTPUT
	A	Transducer A
	B	Transducer B
	AVGE	Average of A+B or $(A+B) \div 2$
	DIFF	Difference of A and B or A-B
	SUM	Sum of A and B or A+B

**Note:** To display these outputs with a 635/636 Monitor, select channel A on the 635/636.

#### 3.2 Gain Range Switches

On units up to Mod 10K these are DIL slide switches which increase amplifier gain by about x3 for each position from 1 to 8.

On units from Mod 11 onwards these are 4-way DIL toggle switches where the same 8 gain ranges are available. When used with the fine gain potentiometer. It allows a continuous gain variation covering a wide range of transducer signals as shown below.

Up to Mod 10K	Mod 11 onwards	Input Signal Range (Vrms) for $\pm 10V$ output
Switch Position	Toggles ON	
1	1	4V max. See Note 1
2	1 + 2	4V max. See Note 1
3	1 + 3	2-4V max.
4	1 + 4	0.7 – 2.4V
5	None	260-850 mV
6	2	90-290mV
7	3	33-100mV
8	4	12-38mV

**Note 1** Ranges 1 and 2 are used to produce lower outputs than  $\pm 10V$ , with high input signals, e.g. for scaling the 635/6 monitors with full scale values much lower than the 19999 maximum.

For example, to display 20.00 full scale with a 3V signal, using range 3 would not allow an output of <5V (50.00 display). Hence range 2 is required.

**Note 2** When using SUM (A+B) mode, ensure that the sum value does not exceed 10v, e.g. if A = 8V, B = 6V, then A+B = 14V (overrange). In this case, reduce amplifier gain so that maximum A and B signals are, say, 5V.

#### 3.3 Fine Gain Potentiometers

These are 20-turn, screwdriver-adjusted controls providing about 3:1 gain change, to interpolate between ranges of the gain switches.

### 3.4 Zero Range Switches

<p>These are 6-way DIL toggle switches used to inject different amounts of zero suppression of the output signal, e.g. to obtain a unipolar output signal from a bipolar LVDT.</p> <p>The amplitude and polarity of the output shift provided by the various settings are shown below. Note these will vary according to the Fine Gain setting.</p>	Toggles ON	Approx. Output Shift (V)
	None	0
	1	+2 to +7
	1 + 3	+4 to +10
	1 + 4	+6 to +10
	1 + 5	+8 to +10
	2	-2 to -7
	2 + 3	-4 to -10
	2 + 4	-6 to -10
	2 + 5	-8 to -10

### 3.5 Fine Zero Potentiometers

These are 20-turn, screwdriver-adjusted controls providing a small adjustment of amplifier output offset to interpolate between the ranges of the Zero Range Switches.

### 3.6 Zero Input Switches

These are momentary action push-buttons which switch the amplifier input signal to zero volts, irrespective of the transducer signal. This allows a true amplifier output zero to be obtained. Refer also to Section 3.12.

### 3.7 Channel Number (Address) Switch

This is a 16-way (hexadecimal), screwdriver-adjusted rotary switch scaled 0 to F. when the module is used in a system with a backplane, the individual channel address number must be set on this switch.

Each module must have a different number set to avoid signal contention on the A, B and E (excitation) output busses to the monitor.

For example, if the switch is set to 1 then, when the monitor switch is set to 1, only the outputs of No.1 are enabled and connected to the monitor. Similarly, for numbers 2 - 9. For modules 10 - 15, the switch positions A - F are used, as shown below:

Module No	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Switch Posn	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F

### 3.8 Frequency Resistor

On units up to Mod 10K, the excitation frequency may be changed by changing one resistor R5, using the formula:

$$R5 = 10 ((8.7/F)-0.15),$$

where R is in kΩ, f is in kHz

For 5kHz excitation	R5 = 16k
For 10kHz excitation	R5 = 7.2k

On units from Mod 11 onwards, this facility is not available. Other excitation frequencies are available but must be stated when ordering.

### 3.9 Output Voltage/Current Selector

Output A (the output corresponding to the mode selected on the front panel) is not selectable and has an output of voltage only.

Output B (channel B) has the facility to select voltage or current output using SP3 for Channel B.

For voltage output, link B - C,
For 4-20mA output, link D - C.

### 3.10 Half-Bridge/Differential Completion Resistors

When using this type of transducer, the amplifier input bridge circuit must be completed by fitting two extra resistors. For Channel A these are R13 and R14. For channel B, R56 and R57. These should be high stability types (e.g.  $\pm 0.1\%$  15ppm) and the normal value is 1k $\Omega$ .

### 3.11 Master/Slave

To eliminate beating effects in multi-channel systems, any one of the modules may be designated as a master oscillator, with all other channels as slave oscillators synchronised to the master.

For the master oscillator, SP6 must be linked B - C.  
For the slave oscillators, SP6 must be linked A - C.  
and SP9 (on rear of board) removed.

To complete the master/slave connections, pin 21 of each card must be linked together. When a 600-type backplane is used, this automatically links pin 21.

NOTE: 626 modules of Mod 11 onwards cannot be made slaves to older pre-Mod 11 modules. If in doubt, contact RDP.

### 3.12 LEDs

These are bi-colour indicators mounted on the front of the module. They change from green to red as the armature passes centre-stroke from in to out. This may be used as an approximate indication only.

## 4. SETTING UP PROCEDURE

- 4.1 Determine the transducer output from the manufacturer's data and set the Coarse Gain control as shown in Section 3.2.
- 4.2 Connect the transducers as detailed in Section 2. Switch on power and allow a 15-minute warm up period (for maximum accuracy).
- 4.3 Press the ZERO/INPUT switch and adjust the ZERO controls for zero output as shown in Section 3. (For 4-20mA outputs, "zero output" = 12mA.) Release the switch.
- 4.4 Adjust the transducer armature for zero output (12mA). the FINE ZERO control may be used to obtain an absolute zero indication if the armature adjustment is too coarse. This determines the transducer centre-stroke position.

Now proceed with either 4.5 or 4.6 according to application.

### 4.5 Half-Stroke Operation

- (a) Move the transducer armature by a precise amount (e.g. 0.200 inches for a D5/200 transducer) and adjust the FINE GAIN control for the desired output, e.g. 10v or 20mA.
- (b) Relocate the transducer armature at the centre of the stroke and check that the output is zero. Re-adjust the FINE ZERO control if necessary.

Repeat (a) and (b) for consistent results.

- (c) Move the armature to the full-scale position in the opposite direction and check for, e.g. -10v or 4mA output.

### 4.6 Full Stroke Operation

If it is required that the transducer be used over its entire working range in one direction, e.g. 0 to 0.4 inches for a D5/200 transducer, then the zero controls are used to "back off" the signal equivalent to 0.200 inches.

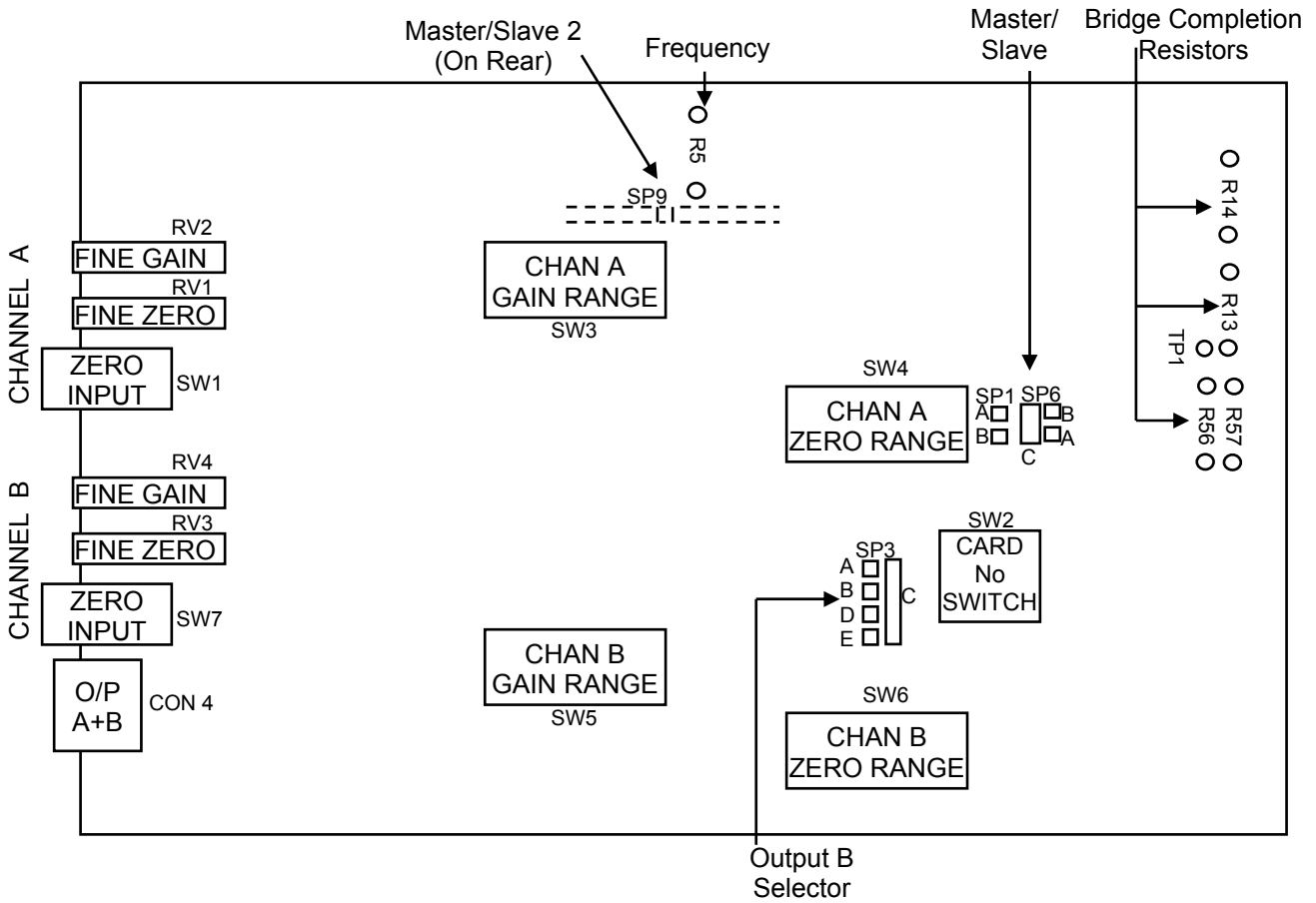
- (a) Set up as in 4.5, i.e.  $\pm 5V$  output for  $\pm 0.2$  inches using a D5/200.
- (b) Move the armature by exactly 0.200 inches (for a D5/200 transducer) and then adjust the ZERO controls to back-off this signal to zero. Now move the armature back 0.400 inches and adjust the FINE GAIN control for the required output.
- (c) Repeat (b) until consistent results are obtained. If, for any reason, the coarse gain is changed, restart the whole procedure.

### 4.7 Differential Inductance Transducers

These devices have a single winding which is centre-tapped to form two active arms of a bridge circuit. To complete the bridge, two dummy bridge resistors are required as shown in Section 2. Refer also to Section 3.10.

Setting up procedure is similar to that described for LVDTs above.

Fig. 3 Control Locations



**NOTE:**

Frequency resistor R5 is not available on units from Mod 11 onwards. Other excitation frequencies are possible but must be stated when ordering.

**5. SPECIFICATION**

Number of Channels:	2 (A and B), common excitation
Supply:	$\pm 15V$ , $\pm 0.6V$ unregulated. 65mA typical, no load.
Excitation:	1.1V, 5kHz, 100mA max.
Signal Range:	12mV to 4V in 8 ranges for $\pm 10V$ output.
Input Impedance:	100k ohms
Zero Range:	$\pm 100\%$ of Output
Output linked for: V:	$\pm 10V$ into 2k ohm (min.)
“ “ I:	4-20mA into 0-450 ohm (Channel B only)
Ripple: (Voltage Output):	10mV p-p typical
(Current Output):	100 $\mu$ A p-p
Bandwidth:	500Hz flat
Linearity:	$\pm 0.05\%$ typical
Crosstalk:	0.01% maximum effect
Operating Temperature:	0 to 60°C
Zero Tempco:	$\pm 0.005\%$ FS/°C
Gain Tempco:	$\pm 0.005\%$ FS/°C
Dimensions:	160 x 100 x 15mm (Eurocard) (6.3 x 4 x 0.6 inches)
Front Panel:	128 x 25mm (5 x 1 inches)
Computation Accuracy:	$\pm 0.02\%$

## 6. WARRANTY AND SERVICE

### WARRANTY.

R.D.P. Electronics products are warranted against defects in materials or workmanship. This warranty applies for one year from the date of delivery. We will repair or replace products that prove to be defective during the warranty period provided they are returned to R.D.P. Electronics.

This warranty is in lieu of all other warranties, expressed or implied, including the implied warranty of fitness for a particular purpose to the original purchaser or to any other person. R.D.P. Electronics shall not be liable for consequential damages of any kind.

If the instrument is to be returned to R.D.P. Electronics for repair under warranty, it is essential that the type and serial number be quoted, together with full details of any fault.

### SERVICE.

We maintain comprehensive after-sales facilities and the instrument can, if necessary be returned to our factory for servicing.

Equipment returned to us for servicing, other than under warranty, must be accompanied by an official order as all repairs and investigations are subject to at least the minimum charge prevailing at the date of return.

The type and serial number of the instrument should always be quoted, together with full details of any fault and services required.

### IMPORTANT NOTES.

1. No service work should be undertaken by the customer while the unit is under warranty except with the authorisation of RDP Electronics.
2. If the instrument is to be returned to R.D.P. Electronics for repair, (including repair under warranty) it is essential that it is suitably packed and that carriage is insured and prepaid. R.D.P. Electronics can accept no liability whatsoever for damage sustained during transit.
3. It is regretted that the above warranty only covers repairs carried out at our factory. Should the instrument have been incorporated into other equipment that requires our engineers to perform the repair on site, a charge will be made for the engineer's time to and from the site, plus any expenses incurred.

The aforementioned provisions do not extend the original warranty period of any product that has been either repaired or replaced by R.D.P. Electronics.

**THIS WARRANTY MAY BE NULL AND VOID SHOULD  
THE CUSTOMER FAIL TO MEET OUR TERMS OF PAYMENT.**